

A STUDY ON MECHANICAL AND SLIDING WEAR BEHAVIOUR OF E-GLASS FIBRE REINFORCED EPOXY COMPOSITES

A THESIS SUBMITTED IN PARTIAL FULFILLMENT OF
THE REQUIREMENTS FOR THE DEGREE OF

Master of Technology

in

Production Engineering

By

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JUNE 2014

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CERTIFICATE

This is to certify that the thesis entitled “**A STUDY ON MECHANICAL AND SLIDING WEAR BEHAVIOUR OF E-GLASS FIBRE REINFORCED EPOXY COMPOSITES**”, submitted to the National Institute of Technology, Rourkela by **Mr. Abhishek Kumar**, bearing Roll no. 212ME2330 in partial fulfilment of the requirements for the award of Master of Technology in the Department of Mechanical Engineering, National Institute of Technology, Rourkela, is an authentic work carried out by him under my supervision and guidance.

To the best of my knowledge, the matter embodied in the thesis has not been submitted to any other university/institute for the award of any Degree or Diploma.

Date: 03/06/2014

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Acknowledgement

With deep regards and profound respect, I avail this opportunity to express my deep sense of gratitude and indebtedness to **Prof. Sandhyarani Biswas, Department of Mechanical Engineering, NIT Rourkela**, for introducing the present research topic and for her inspiring guidance, constructive criticism and valuable suggestion throughout this research work. It would have not been possible for me to bring out this report without her help and constant encouragement.

I express my sincere gratefulness to **Prof. K. P. Maity**, Head of the Department, Mechanical Engineering, NIT Rourkela for giving me an opportunity to work on this project and allowing me the access to valuable facilities in the department.

I am thankful to Mr. Vivek Mishra and Mr. Prabina Kumar Patnaik, Ph.D. scholars of Mechanical Engineering Department and Mr. Arvind Kumar of Ceramic Engineering department and Prof. J.P. Kar of Physics department for their valuable supports.

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Abstract

Due to increasing demand and widespread application of Fibre reinforced polymer (FRPs) composites, they have been used in a variety of application like aerospace, automotive, sports, ships and constructional work. Because of their several advantages such as relatively low cost of production light weight, easy to fabricate and superior strength to weight ratio. In the present work E-glass fibre is used as reinforcing agent with and without alumina filler. The objective of the present research work is to study the mechanical and abrasive wear behaviour of coated and uncoated E-glass fibre reinforced epoxy based composites. The effect of fibre loading and filler content on mechanical properties like hardness, tensile strength, flexural strength and impact strength of composites are studied. A robust design technique called Taguchi method is also used to determine the optimal condition for specific wear rate of the composites by considering different parameters. ANOVA study is also performed to study the effect of various factors on the sliding wear behaviour of the composites. Surface morphology of composites was studied by optical microscope.

Keywords: coating, *e-glass fibre*, *epoxy*, *filler*, *surface morphology*, *taguchi method*

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CHAPTER 1

INTRODUCTION

1.1 Background and Motivation

A combination of two or more materials with different properties, or a system composed of two or more physically distinct phases separated by a distinct interface whose combination produces aggregate properties that are superior in many ways, to its individual constituents. A new material with combination of two or more material can provide enhanced properties that produce a synergetic effect [1].

In composite materials there are two constituents one is matrix and other is reinforcement. The constituents which is continuous and present in greater quantity is called matrix. The main functions of the matrix is to holds or bind the fibre together, distribute the load evenly between the fibres, protect the fibre from mechanical and environmental damage and also carry interlaminar shear. While the other constituent is reinforcement; its primary objective is to enhance the mechanical properties e.g. stiffness, strength etc. The mechanical property depends upon the shape and dimensions of reinforcement [1]. On the basis of type matrix material, composites can be grouped into three main categories, polymer, metallic and ceramic. While on the basis of reinforcement classification of composite is shown in Figure 1.1 below:

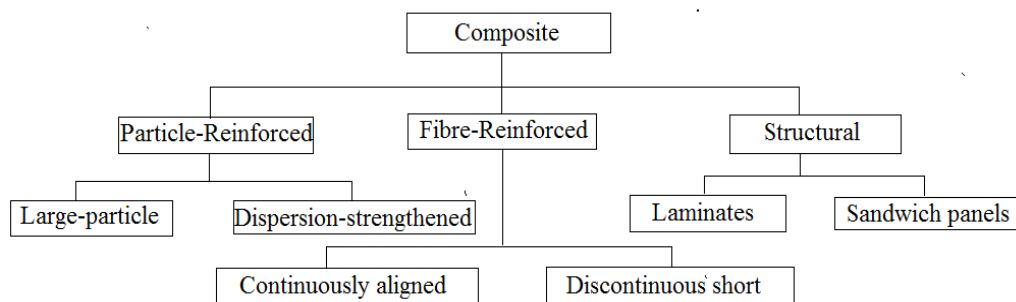


Figure 1.1 Classification of composite based on the type of reinforcement [1]

The main elements of polymer matrix composite are resin (matrix), reinforcement (e.g. fibre, particulate, whiskers), and the interface between them. The present work deals with the fibre reinforced polymer. FRP's offers significant advantages, like combination of light weight and high strength to weight ratio and it is way easy to fabricate which is better than many metallic components [1].

The matrix of FRPs is further classified into-

- I. Thermosetting resin
- II. Thermoplastic resin

Thermoset resin (e.g. polyester, vinyl esters and epoxy) undergo chemical reaction that cross link the polymer chain and thus connect the entire matrix into three dimensional network due to this they possesses high dimensional stability, resistance to chemical solvent, and high temperature resistance. On the other hand unlike thermoset, curing process of thermoplastic resin (e.g. polyamide, polypropylene, and polyether-ether-ketone) is reversible. Their strength and stiffness depends on the molecular weight. They are generally inferior to thermoset in case of high temperature, strength, and chemical stability but are more resistant to cracking and impact damage [2].

As far we concerned about the reinforcement, there are wide variety of it, like natural fibre (e.g. hemp, kenaf, sisal, coir, jute etc), synthetic fibre (e.g. glass fibres, ceramic etc) and organic fibre (e.g. aramid). Natural fibres are cheap, easily available, and bio-degradable but these advantages are not sufficient to overcome their major drawbacks like moisture absorption, It can be easily attacked by chemicals and has low strength compared to synthetic fibres. Now, in manmade fibres there are two types of fibres,

1. Synthetic fibre
2. Organic fibre

There are numerous types of synthetic fibres such as nylon, acrylic, polyester, glass fibres etc. Now a day most commonly used synthetic fibre is glass fibres. There are also varieties of glass fibres e.g. A-glass, C-glass, D-glass, E-CR glass, E-glass and S-glass, among them E-glass and S-glass are most widely and commonly used, in many industry they represent over 90% of reinforcements used. Glass fibres which are available commercially are mainly manufacture in the form of woven roving (cloth), chopped strands, long continuous fibres, Woven roving's consist of continuous roving, which is a fabric are woven in two mutually perpendicular directions. In chopped strand, continuous fibres are cut to the short length and fibres are arranged in the form of bundle [3]. On the other side S-glass has higher tensile strength, greater modulus and higher elongation at failure compared to the E-glass, and S-glass is mainly used where strength is a primary concern along with weight e.g. airplane fuselage, tail wings of airplane, pipes for carrying aqueous liquid, ship hulls, helicopter blades, tanks and vessels. But its cost is primary issue which restrict its application in commonly used items like household appliances e.g. fibre glass doors, window frame, bath tub etc. and sports items e.g. hockey sticks, fishing rod, arrow of archery etc. [5]. The different types of glass fibres are listed in the Table 1.1 below.

Table 1.1 Different types of glass fibres [4]

Type	Composition	Characteristics	Application
A-glass	Alkali-lime with little boron oxide	Not very resistant to alkali	When alkali resistance is not a requirement
C-glass	Alkali lime with high boron oxide content	Resistant to chemical attack	When higher chemical resistance required
D-glass	Borosilicate	High dielectric constant	When high dielectric constant is preferred
E-glass	Alumino-borosilicate with alkali oxides less than 1%	Not chloride ion resistant	Mainly for glass reinforced plastics
E-CR-glass	Alumino-lime silicate with alkali oxides less than 1%	High acid resistance	When high acid resistance is required
S-glass	Alumino silicate with high content of MgO	High tensile strength among all types of fibres	Aircraft components, missile casings

In E-glass fibre the term “E” stands for electric, which is made from alumino- borosilicate glass containing oxides of alkali less than 1% by weight, C-glass has high content of boron oxide, whereas S-glass having high content of magnesium oxide with silica and aluminium oxide [4]. The typical composition of different glass fibres are shown in the Table 1.2 given below.

Table 1.2 Composition and properties of glass fibres [1]

Compositions (%)	E-glass	C-glass	S-glass
SiO ₂	52.4	64.4	64.4
Al ₂ O ₃ + Fe ₂ O ₃	14.4	4.1	25.0
CaO	17.2	13.4	-
MgO	4.6	3.3	10.3
Na ₂ O + K ₂ O	0.8	9.6	0.3
B ₂ O ₃	10.6	4.7	-
BaO	-	0.9	-
Properties			
Density (gm/cm ³)	2.60	2.49	2.48
Thermal Conductivity (W/mK)	13	13	13
Coefficient of Thermal Expansion (10 ⁻⁶ K ⁻¹)	4.9	7.2	5.6
Tensile Stress (GPa)	3.45	3.30	4.60
Elastic Modulus (GPa)	76	69	85.5

Organic fibre- The commonly used organic fibre derived from aromatic polyamides possesses high modulus, are called aramid fibres. They were first developed by Du Pont with the trade name “*Kevlar*”. They derived from the polymer molecules those have high degree of aromaticity (containing benzene rings in their structure) which possesses crystalline behaviour in liquid solution. They are usually produced from spinning and extrusion process [1]. Its common application are in rail carriage, for temperature resistance environment like hoses, tyres, brake pads and belts, ballistic helmets in military applications. Due to its

property like high tensile strength, light weight and dielectric property it is also used in wide variety of optical fibre applications.

In the present work randomly oriented short E-glass fibre is used as reinforcing agent because of its good strength, light weight, chemical resistance and more importantly its low cost. Aluminium oxide (Al_2O_3) also called as alumina is used as a filler material. The addition of filler to the composites enhances the mechanical as well as physical properties [6]. The properties of Al_2O_3 like chemical inertness, high hardness, good strength and less expensive made it fit for the use where friction and wear conditions are predominant e.g. for low cost automotive brake linings [7]. Pure aluminium is chosen as coating material because of its wear and corrosion resistance property due to its passivation effect (it is the property of material to form thin coating film of its oxide and prevents its surface from foreign factors e.g. air and moisture) [8]. And also filler material is compound of aluminium.

1.2 Thesis Outline

The rest of the thesis work is summarized as follows:

Chapter 2: This chapter includes literature review related to present research work is detailed in this chapter.

Chapter 3: This chapter provides detail description of material, their fabrication techniques and description of composites for different tests were investigated and robust design method called Taguchi experimental design is explained.

Chapter 4: This chapter deals with analysis of experimental result of physical and mechanical properties of composites.

Chapter 5: In this chapter experimental result of wear rate are analysed and selection of optimizing parameter is done by Taguchi method.

Chapter 6: This chapter presents the conclusions and scope of future work.

CHAPTER 2

LITERATURE SURVEY

This chapter reveals the upbringing information on the topic to be considered in present research work and focuses on the importance of current study. The objective is to analyse the effect of various parameters influencing the mechanical and wear behaviour of FRPs composite. The literature survey is based on the following aspects:

2.1 On mechanical properties of E-glass reinforced epoxy composites

Rout et al. [9] investigated the mechanical properties and erosion wear of glass fibre reinforced epoxy composite with filled and unfilled rice husk particulates. Experimental design was also done using Taguchi optimization technique to determine the optimal parameters, which minimizes the wear rate. They concluded that factors like filler content, impact velocity, impingement angle and erodent size has more significant effect on wear rate, and at 15 wt% of rice husk shows maximum wear resistance. Tensile modulus, hardness and impact energy improves with addition of filler content. Decline in flexural and tensile properties of the composites were noticed. Al-Hasani [10] studied the tensile strength and hardness of glass fibre reinforced epoxy composite at different volume fraction as layers. Three types of composite samples were prepared, woven roving, randomly oriented and sandwich which consists of (woven roving and Random oriented). It was found that sandwich composite exhibits higher value of tensile strength 254 N/mm^2 whereas, nine layered glass fibre woven roving composites exhibited higher hardness of 62.1 BHN.

Koricho et al. [11] studied the bending fatigue behaviour of twill E-glass epoxy composite. Bending fatigue behaviour of composites specimens were analysed by displacement controlled bending fatigue test. Samples were subjected to different fatigue

loadings with maximum level up to 0.75 times the ultimate flexural strength of the material, After 1 million cycles residual properties of selected specimen were measured. They found experimentally that tensile stresses are damaging while compressive stresses are beneficial.

Deng et al. [12] experimentally investigated the influence of different types of E-glass fibre cross-section (round, oval and peanut-shaped) aspect ratio on interlaminar shear strength, interlaminar fracture toughness, and charpy impact test. They reported that delamination resistance of composites is lower for the composites having larger fibre cross-section compared to the composites reinforced with round cross-section, because of the fibre overlapping. Same trend were observed for different tests like double-cantilever beam (DCB), short-beam-shear (SBS), and end-notched flexure (ENF) and however larger aspect ratio fibre reinforced composite shows better energy absorbing capacity than composites reinforced with conventional round fibres.

Alvarez et al. [13] conducted three point bending test with Perkin Elmer DMA-7 equipment to determine loss modulus, storage modulus, and loss factor of unidirectional glass fibre reinforced epoxy resin. Two different types of epoxy resin were used to coat the fibres and their viscoelastic properties were determined. Span to thickness ratio L/h should be higher than 15 for good results, because modulus is constant for all settings.

2.2 On sliding wear behaviour of fibre reinforced polymer composites

El-Tayeb et al. [14] had carried out experimental study on frictional and wear behaviour of a unidirectional E-glass reinforced epoxy composite. Wear rate and friction coefficient was calculated under different sliding velocities, normal applied load for various surface conditions (e.g. dry, wet, lubricated conditions) using pin on disc apparatus while load is applied normal to the fibre orientation. The wear and frictional behaviour of composite is dominated by surface conditions of counter face, e.g. wet and clean surfaces

improves the friction coefficient and wear rate. It was also observed that minimum value of friction coefficient and wear rate was obtained in case of water lubricated conditions which depend on applied normal load and speeds. Friction coefficient and wear rate was decreased in all cases when either the load or speed decreases.

Lu et al. [15] investigated the wear and frictional behaviour of blends of PEEK with polytetrafluoroethylene (PTFE), polyether-ether ketone and carbon fibre reinforced PEEK composites using a pin on disc apparatus. The experiment was performed by sliding specimens against hard steel under dry sliding conditions. The study shows that wear rate of higher molecular PEEK was better than lower molecular PEEK and also this effect was more significant at higher values of load and rpm. But the friction coefficient had not clear variation with combination of load and rpm. Addition of PTFE to PEEK lowered the friction coefficient, which is minimum at 15% and wear rate is minimum when 5% of PTFE added up to PEEK. Wear rate and friction coefficient were also affected by variation of temperature and it is observed that at 10% volume of carbon fibre the wear rate is minimum. The further increase in fibre volume caused stick slip phenomenon to occur at higher testing temperature.

Ramesh et al. [16] had studied the tribological behaviour and microstructure of nickel coated silicon nitride (Si_3N_4) particles under dry sliding condition. Friction and wear test were conducted on pin on disc apparatus over a range of load varies from 20-100N and sliding velocities in the range from 0.31-0.157 m/s. Results shows that, distribution of nickel coated Si_3N_4 particles was uniform in the entire matrix. The friction coefficient for composite was decreased when load increased up to 80N, but further increase in load raised the friction coefficient. Wear rate of composite depend both on sliding velocity and load applied, i.e. its rate increased with continuous increase in load and velocity. However, friction coefficient of composite was increased only with increasing sliding velocity. Surface morphology was examined using SEM to observed wear mechanism. XRD and EDS were also used to detect

the oxide formation on worn surfaces. The Ni coated Si_3N_4 particle reinforced matrix shows lower value of friction coefficient and wear rate than unreinforced alloy matrix. And also the formation of oxide layer at the interface reduces the friction and wear rate.

Basavarajappa et al. [17] studied the sliding wear behaviour of glass-epoxy laminate composite made by hand lay-up technique filled with both silicon carbide and graphite under dry sliding condition, by pin on disc apparatus. The volume fraction of filler was varied in the range of 5-10% for SiC and kept constant for graphite at 5%. The transfer film was formed on the counter surface improves wear resistance of glass-epoxy composite. Impact of applied load on wear rate was more prominent compared to other constraint like sliding velocity and sliding distance. In premature stage the wear rate of composite was significantly affected by presence of filler. The abrasive wear depends on composition of filler as well as nature of formation of transfer film against counter surface. SEM images were used to observed fibre breakage, fibre debonding from matrix and debris formation.

Soussia et al. [18] investigated the dry cutting of glass-epoxy composite for different variety of coating. The experiments were done with different orientation of glass fibre at 0° , 45° , and 90° on three different samples in the cutting direction. Three different inserts e.g. CVD diamond coated, uncoated tungsten carbide, and multi-layer titanium coated were used to perform cutting test. They found that wear resistance depends upon type of orientation and coating type. CVD diamond coated had better wear resistance at 0° orientations but at 45° and 90° fibre orientation it leads to the catastrophic failure. Uncoated WC had lowest flank wear. The adhesive property of the epoxy increased the thermal conductivity of the matrix. Multi layered coated tool showed better dissipation of thermo-mechanical energy due to good adhesion between coating layer and substrate.

Basavarajappa et al. [19] studied the wear behaviour of glass-epoxy composite filled with graphite under dry sliding conditions. Experiment investigation using a pin-on-disc apparatus was done under different load, sliding distance and sliding velocity to understand the comparative performance of glass-epoxy composites with the influence of graphite filler. They found that lower weight loss of the composite on increasing the graphite percentage in the composites. The wear rate of unfilled glass-epoxy was higher compared to graphite filled, because graphite serves as lubricant and it forms thin film which transferred on the counter surface and moderate the effect of three body abrasion. SEM micrographs revealed the formation of debris, fibre breakage, debonding between fibre and matrix under varying load, sliding velocity and sliding distance.

Sampathkumaran et al. [20] analysed the SEM topographies of glass-epoxy laminate composite under dry sliding condition for varying distances in the range from 500m to 6000m. Authors found different changes in worn surfaces at different sliding distances. For the shorter distances wear debris was formed and also sometimes fragmentation of glass fibre were seen. While for longer distances separation of interface occurred. They concluded that on subjecting the specimens to wear conditions, particularly in the sliding distance range of 0.5 km–6 km features like increased matrix debris formation, fibre breakage and exposed transverse and longitudinal fibres were observed.

Andrich et al. [21] had investigated the wear and frictional behaviour of glass fibre reinforced polypropylene composite and carbon fibre reinforced epoxy composite against coated and uncoated 100Cr6 steel. They used diamond like carbon (DLC) as coating material. Tribological properties were improved by using suitable fibre reinforcement. They mainly focus on the development of the new materials those are loaded in their tribological applications. The carbon fibre reinforced composite showed remarkable improvement in wear

rate against DLC coated steel counter surface and shows its potential application for sliding bearing material.

Kishore et al. [22] studied the sliding wear behaviour of glass/epoxy composite filled with different types of filler like rubber and oxide particles for bearing application, using back on roller arrangement. They calculated weight loss as a function of sliding distance for different sliding velocity ranges from 0.5 to 1.5 m/s at three different loading settings 42, 140, and 190N respectively. SEM was used to observe worn surfaces morphology. They found that, oxide filled composites had lower wear at low load but for rubber filled composite wear rate was lower at higher load. They also reported inclined fibres fracture, interface separation and loss of matrix as well as the presence of debris with two different fillers at higher sliding velocity and load conditions of wear. The work shows the dependency of wear system on type of filler used and their pattern.

Suresha et al. [23] studied the two-body abrasive wear and mechanical behaviour of glass and carbon reinforced vinyl ester composite. They observed a rise in wear weight loss with increase in particle size of abrasive and abrading distance. But specific wear rate shows opposite outcome to wear volume loss, it decreases with abrasive particle size and abrading distance. The study reveals the higher wear loss of glass/vinyl composite in comparison to carbon/vinyl composite with increasing abrading distance. Because of the higher specific strength and self-lubricating property of carbon fibre, it exhibits superior abrasion resistance than glass fibre under different loading and sliding distance conditions. The result shows that higher wear rate for the glass fibre composite was $10.89 \times 10^{-11} \text{ m}^3/\text{N-m}$, whereas for carbon fibre composite its value was $4.02 \times 10^{-11} \text{ m}^3/\text{N-m}$.

2.3 Effect of coating on wear behaviour of fibre reinforced polymer composite

Kim et al. [24] Studied the effect of coating material like epoxy and polyethylene mixed with self-lubricating powder molybdenum disulphide and PTFE powders on the tribology of carbon reinforced epoxy prepreg composites with many grooves on its surfaces, under dry sliding and water loosened conditions. When the surface was coated with self-lubricating powder it significantly improve the wear resistance by blocking water to enter into the grooves of composite and coating also reduces the formation of blister for water loosened conditions. When either of the epoxy or polyethylene mixed with MoS_2 , friction coefficient was reduced by 9% compared to the epoxy or polyethylene containing PTFE powder. The mixture of polyethylene and MoS_2 has imparted excellent wear resistance by arresting hard particles into coating layer.

Pan et al. [25] analysed the effect of two phase composite coating on graphite-epoxy composite. The surface resistance decreased with the addition of graphite after seepage critical value (SCV) and conductivity increases. They observed that when the graphite content exceeds to 40% the conductivity of the graphite-epoxy composite increased and surface resistance decreases because of that. But, on the other hand adhesion of coating decreases due to higher graphite content. Similar graph were obtained for wear rate vs. graphite content and friction vs. graphite content both model shows the two valleys. They found that at graphite content less than 40%, epoxy appeared as a continuous phase and graphite as dispersed phase whereas, reverse of this happened when graphite content was greater than 40%.

Bakshi et al. [26] studied the wear and microstructure of the composites with coating of aluminium and Al- 11.6 wt% silicon eutectic alloy phases of varying composition prepared by cold spraying. The micro hardness of coatings was enhanced with increase in volume

fraction of Al-Si coating. They observed similar volumetric wear loss for both Al and Al-Si coated composites in spite of increased micro hardness of Al-Si composite. This may be due to inter-splat delamination mechanism.

Conradi et al. [27] investigated anti-corrosion and mechanical behaviour of Nano-silica filled particle epoxy resin composite coating. For this study composites with two different coatings were prepared. Epoxy coating of 50 μm thickness and another coating of epoxy which contained 2 wt% of silica Nano particle of 130 nm size were applied over the surface of austenitic stainless steel. Vickers hardness tester and Profilometer were used to understand the mechanical properties and surface morphology, respectively. The effects of addition of silica particle on corrosion resistance and surface characteristics were determined by measuring contact angle as well as by potential dynamic polarization and electrochemical impedance spectroscopy in a 3.5 wt% sodium chloride solution. They observed that addition of silica particle considerably advanced the microstructure of coating matrix. This leads to the increase in surface roughness, hardness and prompted hydrophobicity. It was reported that Nano-silica coating act as barrier in chloride rich environment which resulted in better anticorrosion performance. The surface energy was lowered by adding Nano-silica to epoxy matrix.

2.4 Objective of the Present Research Work

Keeping in view of the current status of research the following objectives are set for the scope of the present research work.

1. Fabrication of glass fibre reinforced epoxy composites with and without Al_2O_3 filler and evaluation of their mechanical and sliding wear properties.
2. To study the influence of fibre loading and filler content on mechanical and sliding wear behaviour of glass-epoxy composites.

3. To understand the effect of aluminium coating on the sliding wears behaviour of glass-epoxy composites.
4. Parametric analysis of sliding wear process using Taguchi experimental design and to study the effect of various parameters on specific wear rate.
5. To study the surface morphology of the fractured samples using optical microscope.

CHAPTER 3

MATERIALS AND METHODS

This section deals with different material and processing technique used for the fabrication of composite under this present work. It provides the details of tests and characterization which are conducted on composite samples.

3.1 Materials

3.1.1 Matrix

Polymer matrices are most common and widely used matrix material, because of its availability, easiness to fabrication, light weight and low cost compared to others. The matrix material used in the present work is epoxy resin which belongs to the class of thermoset material that contains epoxide group as its functional element in which one oxygen atom is bonded to two carbon atoms.

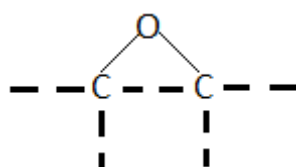


Figure 3.1 The epoxide group [2]

Among all thermoset resin, epoxy resin is widely used as matrix material. It forms three dimensional cross-link structures after undergoing irreversible chemical reaction. It possesses several benefits over other thermoset resin like superior mechanical strength, good bonding with various type of fibres, low shrinkage upon curing and resistant to chemicals. Because of several advantages over other types of resin, epoxy resin LY-556 is picked as matrix material.

Commonly used epoxy is Diglycidyl Ether of Bisphenol-A. The chemical structure of epoxy is shown below.

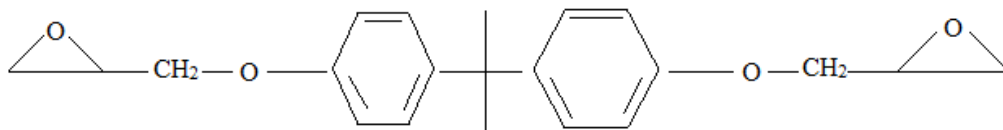


Figure 3.2 Chemical structure of diglycidyl ether of bisphenol-A [2]

3.1.2 Fibre material

Glass fibres are most common reinforcing agent among various composite materials. Glass fibres are available in the form of woven fabric, chopped strands, long continuous fibre and short discontinuous fibre. In present research work randomly oriented short E-glass fibre is used as reinforcing agent. The average length of E- glass fibre is about 6 mm. it is basically an ordinary borosilicate glass containing less than 1% of alkali oxides.



Figure 3.3 Short E-glass fibres

3.1.3 Filler material

Various types of particulate filler are used as reinforcement in polymer based composite. Among them silicon carbide (SiC), alumina (Al_2O_3) and Titania (TiO_2) are most widely used as conventional filler. In the present work alumina (Al_2O_3) is used as filler material. The properties of Al_2O_3 like chemical inertness, high hardness, good strength and less expensive made it fit for the use where friction and wear conditions are predominant.

3.1.4 Coating material

In the present work material aluminium is used as coating material due to its wear and corrosion resistance property due to its passivation effect (it is the property of material to form thin coating film of its oxide and prevents its surface from foreign factors e.g. air and moisture) [8]. And also filler material is compound of aluminium

3.2 Composite Fabrication

3.2.1 Mechanical Testing

In the present work short glass fibre is taken as reinforcing agent. The epoxy resin (LY-556) and hardener (HY-951) were supplied by Ciba Geigy India Ltd. Alumina (Al_2O_3) is used as a filler material, having particle size in the range of 80-100 μm . The short E-glass fibre mixed with epoxy resin and hardener in the ratio of 10:1 by weight with and without use of alumina filler. Then combined mixture is carefully mechanically stirred and poured into different moulds using hand lay-up technique. A mould releasing sheet is used for the easy removal of composites from the mould. The cast is allowed to cure under a load of 20 kg at room temperature 27°C for 24 h. By varying weight percentage of E-glass fibre different composite samples are made (EG-1 to EG-4) with no use of filler material. Other composite samples with varying fibre loading and 5% of alumina (EGA-1 to EGA-3) are also prepared. After curing, samples were cut to the desired dimensions for different mechanical test. The composition and description of composite used in this study are listed in Table 3.1

3.2.2 Wear Test

In case of wear test, the samples are prepared using syringe needle of 2.5 ml volume, of circular cross-section having diameter of 10 mm and 50 mm length. The fibre and filler percentage of the composites, curing temperature and duration remains same as before.

3.2.3 Coating of Composite

Thermal evaporation technique is used for coating of composites. The target material (aluminium) is heated in an evacuated chamber so that it attains a gaseous state. Vapour of this aluminium traverse the space from the source to the substrate [28]. The typical deposition rate for aluminium is ($\sim 8\text{nm/s}$). Aluminium (Al) and Gold (Au) metals are suitable for thermal evaporation system because they can be melting in heated crucible and produces enough quantity of vapours. But in present work aluminium is chosen as coating material because it has low melting point, low cost and easily available. When temperature is high enough, the gas impingement rate $\Phi = \Phi(P_e)$ can cause deposition of material (thin-film) on a substrate ($T_s \ll T$).

Where,

T_s = Substrate temperature and

T = Source temperature

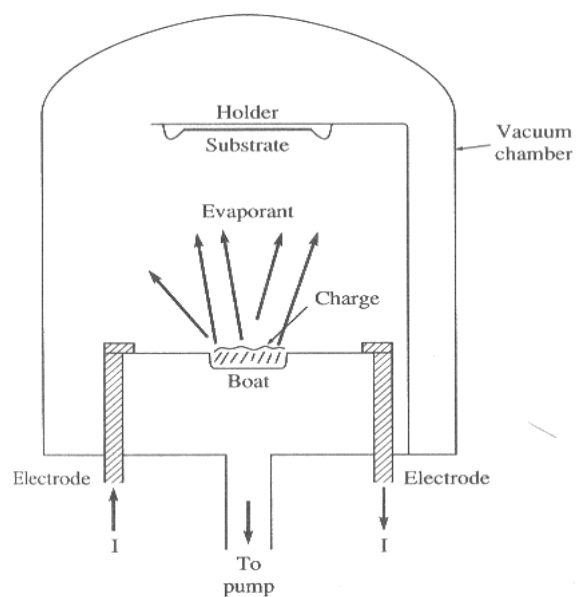


Figure 3.4 Schematic diagram of vacuum evaporation [28]

Table 3.1 Designation of composite

Composites	Compositions
EG-1	Epoxy + E-glass fibre (0 wt%)
EG-2	Epoxy + E-glass fibre (10 wt%)
EG-3	Epoxy + E-glass fibre (15 wt%)
EG-4	Epoxy + E-glass fibre (20 wt%)
EGA-1	Epoxy + E-glass fibre (10 wt%) +Alumina (5 wt%)
EGA-2	Epoxy + E-glass fibre (15 wt%) +Alumina (5 wt%)
EGA-3	Epoxy + E-glass fibre (20 wt%) +Alumina (5 wt%)

3.3 Physical property of composite

The actual density (ρ_c) of composites can be obtained experimentally by water immersion method. The theoretical density of composite materials can be obtained from Agarwal and Broutman equation [29].

$$\rho_t = \frac{1}{\frac{w_f}{\rho_f} + \frac{w_m}{\rho_m} + \frac{w_p}{\rho_p}} \quad (3.1)$$

Where, W_f , W_m , and W_p are the weight fraction of fibre, matrix, and particulate, respectively and ρ_f , ρ_m , and ρ_p are the densities of fibre, matrix and particulate, respectively. The voids volume fraction (V_v) of composites can be calculated as follows:

$$V_v = \frac{\rho_t - \rho_c}{\rho_t} \quad (3.2)$$

3.4 Mechanical testing of composites

The tensile test is conducted on all the samples as per ASTM D3039-76 test standards. Specimens are positioned in the grips of universal testing machine and a uniaxial load is applied through both the ends until it gets failure. During the test, the crosshead speed is taken as 2 mm/min as per ASTM standards, specimens of rectangular cross-sections having length and width of 100 mm and 15 mm respectively are used. Figure 3.5 shows the experimental setup for the tensile test.



Figure 3.5 Experimental set up for tensile test

To determine the flexural strength of composites a three point bending test is performed using (Tinius Olsen H10KS). Before testing width and thickness of specimens measured at different point and mean value is taken. Samples were placed horizontally upon two points and midpoint is perpendicular to loading nose. The crosshead speed for test is maintained at 2 mm/min. Flexural strength in terms of MPa is determined using the equation

$$F = 3PL / 2wt^2 \quad (3.3)$$

Where,

P = Load applied on centre of specimen (N)

L = Span length of specimen (m)

w = Width of specimen (m)

t = Thickness of specimen (m)



Figure 3.6 Experimental set up for flexural test

Hardness of composite samples is measured using Leitz-micro hardness tester. A diamond indenter in the form of right-square pyramid having base angle of 136° is forced on the sample, when load is removed diagonals of indentation (d_1 and d_2) is measured and their arithmetic mean is taken. In present work a load of 0.3 kgf is applied over the composite surface. The following formula used for the calculation for Vickers hardness

$$H_v = 0.1899 \frac{F}{L^2} \quad (3.4)$$

$$\text{And } L = \frac{d_1 + d_2}{2} \quad (3.5)$$

Where, F is the applied load in kgf and L is the arithmetic mean of diagonals made by indenter and d_1 and d_2 are the horizontal and vertical length respectively. The experimental setup for the hardness test is shown in Figure 3.7.



Figure 3.7 Experimental set up for Hardness test

The impact test is performed using swinging pendulum type impact tester. A safety lock holds the pendulum in its raised position and release when activated. Once released, the pendulum quickly hits the V-notched specimen. The testing equipment directly displays the energy absorbed by the broken specimen in a digital panel. The dimension of specimen is $64 \times 12.7 \text{ mm}^2$ and depth of notch is 10.2 mm.

3.5 Sliding wear test of composite

Wear behaviour of composites is studied using a pin-on-disc apparatus under dry sliding condition. Figure 3.8 and 3.9 shows the schematic diagram and pictorial view of pin-on-disc setup, respectively. Wear monitoring setup was supplied by DUCOM and the sliding wear test is performed according to ASTM G99 test standards (standard test method for wear testing with a pin-on-disk apparatus). The specimen is held stationary in pin assembly and counter disc is rotated while the normal load is applied through a lever arm mechanism. Counter disc is made of case hardened steel (72HRC, EN-32, $0.6 \mu\text{m}$ surface roughness). Series of wear test are conducted at different sliding velocities and at normal load. Weight

loss of composites is measured using precision electronic balance with accuracy of ± 0.1 mg.

The specific wear rate of the material is given by the below mentioned equation

$$W_s = \frac{\Delta m}{\rho_c t V_s F_N} \quad (3.6)$$

Where,

Δm = Difference in mass of the samples before and after the test

ρ_c = Density of composite (gm/mm^3)

t = Duration of test (sec)

V_s = sliding velocity (m/s)

F_N = Applied normal load (N)

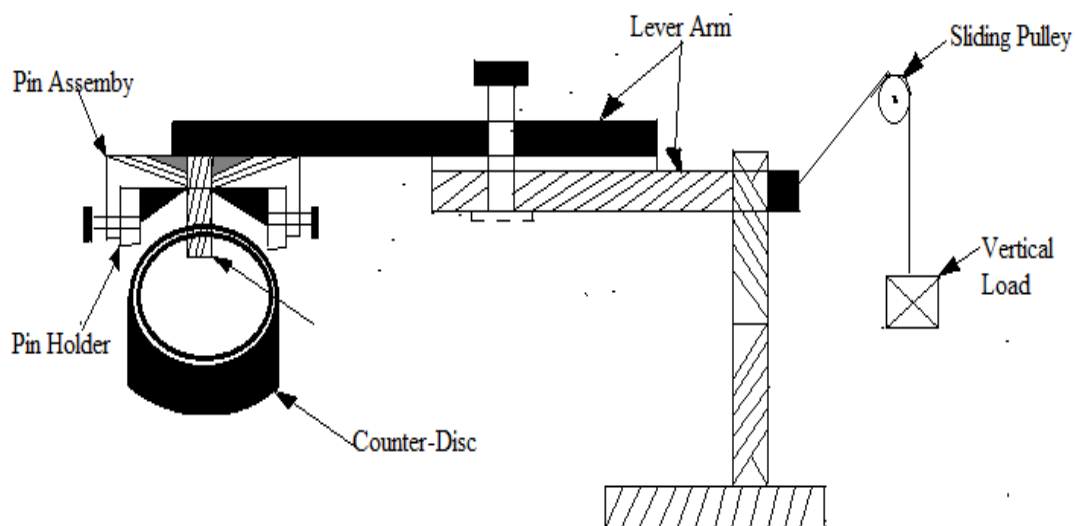


Figure 3.8 Block diagram of “Pin-on-Disc” set up

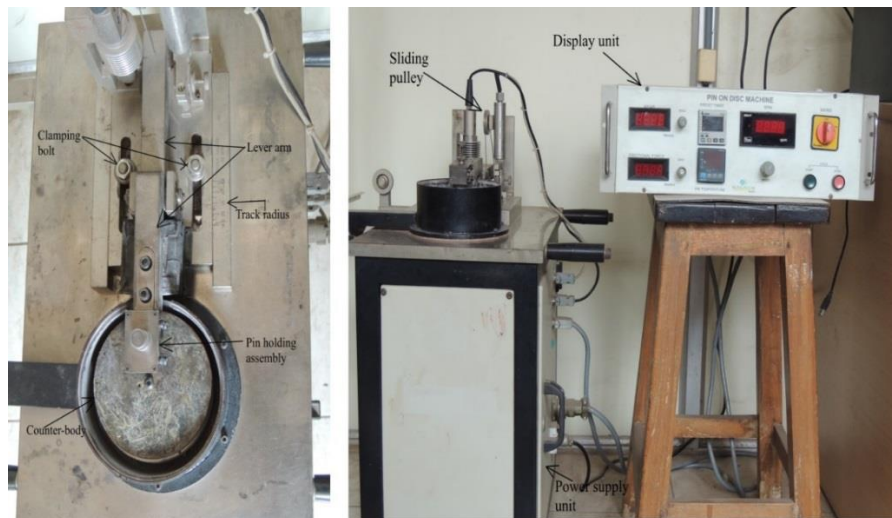


Figure 3.9 Pin on disc set up

3.6 Optical microscope

Zeiss optical microscope is used to view the surface of the composites. It works on Axiom imager microscopy. In bright field microscopy, light from an incandescent source is concentrated on a lens called a condenser, which is used to focus the light on the specimen through an opening stage. After that, light passes through objective lenses and finally to eyepiece lenses through second magnifying lenses. This technique is usually employed for thin section material. Samples are cleaned thoroughly and air-dried for better illumination. Working parameters like voltage, magnification, and contrast depend upon the type of view of specimens.



Figure 3.10 Optical microscope setup

3.7 Taguchi method

Taguchi method is the technique based on performing experiments to test the sensitivity of a test of response variables to a set of control factors (or independent variables) by designing experiments in “*orthogonal array*” with an objective to attain the finest set of control. An array indicates the number of rows and columns and also number of level in each column. The important tools for robust design is Taguchi method, design of experiment (DOE), and regression analysis. For instance $L_4 (2^3)$ has four rows and three “2 level” columns. The no. of rows of orthogonal array represents required number of experiments. The no. of rows must be at least equal to degree of freedom associated with control variables. In present study, four parameters is, sliding velocity, sliding distance, normal load, and fibre loading are set at three levels while filler content and coating thickness set at two levels. Mixed level type $L_{36} (2^{11} 3^{12})$ orthogonal array design is used. Table 3.2 shows the experimental details of control factors and their level.

There are three types of S/N ratios available according to the type of response. For minimum specific wear rate, S/N ratio falls under the category of smaller is better. Mathematically it can be expressed as

$$S/N = -10 \log_{10} \frac{1}{n} (\Sigma y^2) \quad (3.7)$$

Where, n = number of observations and y = observed data

Table 3.2 Experimental details of control factors and their level

Control factors	Levels			Units
	I	II	III	
Filler Content	0	5	-	%
Coating Thickness	0	0.25	-	μm
Sliding Velocity	0.523	0.7854	1.1	m/s
Sliding Distance	314.16	471.3	659.73	m
Normal Load	5	10	15	N
Fibre Loading	10	15	20	%

CHAPTER 4

PHYSICAL AND MECHANICAL CHARECTERISTICS OF COMPOSITES:

RESULT AND DISCUSSIONS

This section presents the results of physical and mechanical properties of short E-glass fibre reinforced epoxy composites with and without alumina filler.

4.1 Physical property of composites

The theoretical and measured density of composite samples with their void volume fraction is presented in Table 4.1. The differences in theoretical and measured densities are the measure of voids present in composite samples. It is difficult to avoid the formation of voids in the composites fabricated by hand layup technique but maximum possible measures were taken to minimize the formation of these voids during the fabrication of the composites. It is necessary to determine the void content of the composites as it effects the property of the material.

Table 4.1 Theoretical and measured densities with void fractions in composites

Sample name	Filler content (%)	Theoretical density (gm/cc)	Measured density (gm/cc)	Void Fraction (%)
EG-1	0	1.15	1.032	10.2
EG-2	0	1.216	1.133	6.8
EG-3	0	1.2532	1.183	5.6
EG-4	0	1.292	1.195	7.48
EGA-1	5	1.2643	1.215	3.9
EGA-2	5	1.3035	1.246	4.41
EGA-3	5	1.345	1.317	2.08

4.2Part-1 Mechanical properties of composites without filler at different fibre loading

The mechanical properties of the short E-glass fibre reinforced epoxy composites at different fibre loading without filler are presented in Table 4.2. It is observed from the Table 4.2 that at 20wt% of fibre loading the composites exhibits better mechanical properties as compared to other composites.

Table 4.2 Mechanical properties of composites without filler at different loading

Composites	Hardness (HV)	Flexural Strength (MPa)	Tensile Strength (Mpa)	Impact Strength (J)
EG-1	18.7	16.41	4.62	0.245
EG-2	23.85	54.5	11.23	4.233
EG-3	24.54	62.2	14.3	3.428
EG-4	25.54	48.3	14.46	3.382

Hardness is one of the most important factors that affect the wear property of materials. The E-glass fibre epoxy composites with different fibre loading, with and without filler is shown in Table 4.2. From the Table it is clear that, with the increase of fibre loading, micro-hardness of the glass epoxy composites increases from 0 to 10 wt% of fibre loading then it shows very little increment in hardness with further increase in fibre loading. This is attributed to the fact that hardness is a function of the relative fibre volume and modulus [34].

The flexural strength of unfilled composites increases with increase in fibre loading up to 15 wt% and then decreases on further increasing the fibre loading. The decrease in flexural strength at 20 wt% fibre loading may be due to insufficient wetting between fibre and matrix because of which stress doesn't transfer properly to the fibres.

The tensile strength value of the composites is shown in Table 4.2. An increase in tensile strength is observed with the increase in the fibre loading in case of glass epoxy

composites without filler. This improvement at higher fibre loading may be attributed to presence of more fibres which act as the load carrying members in the composites [7, 9].

Impact strength of composites without filler increases with fibre loading from 0wt% to 10wt%, after that it decreases irrespective of fibre loading. At higher fibre loading poor distribution and dispersion of fibre may occur due to which the impact strength of the composites decreases [9].

4.2 part-2 Mechanical properties of composites with filler at different fibre loading

The mechanical properties of the short E-glass fibre reinforced epoxy composites at different fibre loading with filler are presented in Table 4.3. It is observed from Table 4.1 that composites with 10wt% of fibre loading with 5 wt% of alumina content i.e. EGA-1 display better flexural and impact strength as compared to others composites. On the other hand EGA-3 and EGA-2 composites exhibit higher hardness and tensile strength values.

Table 4.3 Mechanical properties of composites with filler at different fibre loading

Composites	Hardness (HV)	Flexural Strength (MPa)	Tensile Strength (MPa)	Impact Strength (J)
EGA-1	25.34	75.4	26.19	3.056
EGA-2	31.62	35.65	33.55	1.982
EGA-3	37.28	69.2	22.83	1.277

The hardness of Al_2O_3 filled composite increases from 21.26 to 37.28 Hv. This implies 75% increment in hardness value compared to unfilled composites. During hardness test filler phase and matrix phase pressed together and interface can transfer load more effectively although interfacial bond strength may be poor which results in improved hardness [30].

The flexural strength of filler content composites reduces when fibre loading increases from 10 wt% to 15 wt% this may be due to poor dispersion of particulate and possibility of existence of voids [9, 31]. It is clearly observed from the Table 4.1 that Al_2O_3 filled composite with 15wt% of fibre has more void percentage as compared to Al_2O_3 filled composite with 10wt% of fibre loading. However, the strength increases for Al_2O_3 filled composite with 20wt% of fibre loading as it has low void content.

The tensile strength of the alumina filled composites increases with increase in fibre loading up to 15 wt% after that it decreases for composite with 20 wt% of fibre loading. The improved tensile strength of alumina filled composites up to 15 wt% fibre loading may be due to better dispersion of filler, better wettability and good adhesion between the matrix and filler. The reduction in tensile strength with filler addition may be due to the weak chemical bond strength between filler particles and the matrix body which is unable to transfer the tensile load [9].

For Al_2O_3 filled composites, the impact strength decreases with increase in fibre loading, as observed from Table 4.3. The mobility of polymer chain is arrested by presence of fillers, constrained its free deformation and makes the material less ductile [9]. Thus the ability of the composite to absorb energy has been reduced with the addition of filler.

4.3 Surface morphology of composites before and after tensile test

Figure 4.6 (a) shows the glass fibre reinforced epoxy composites before tensile test. It shows the even fibre distribution in matrix, presence of voids and small patches that indicates the presence of filler in matrix. After applying uniaxial tensile load, layer breakage of matrix takes place, crack propagates through matrix where fibre distribution is uneven i.e. from weakest section of composite which causes localized yielding. Presence of fibres prevents crack formation, but when applied load reached above yield point of material then fibre-

matrix bonding was not sufficient to stand the applied load and it finally breaks down as shown in Figure 4.6 (b).

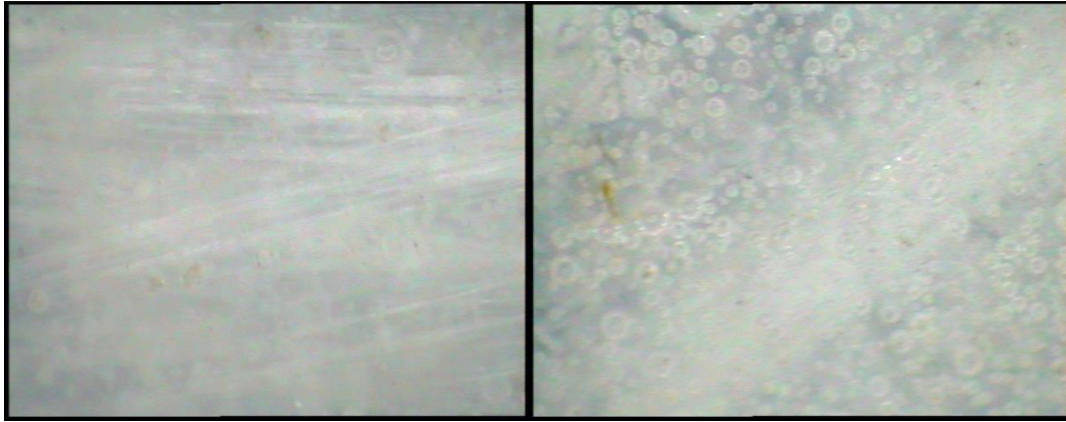


Figure 4.6 (a) Optical microscope images of glass fibre epoxy composite before tensile test

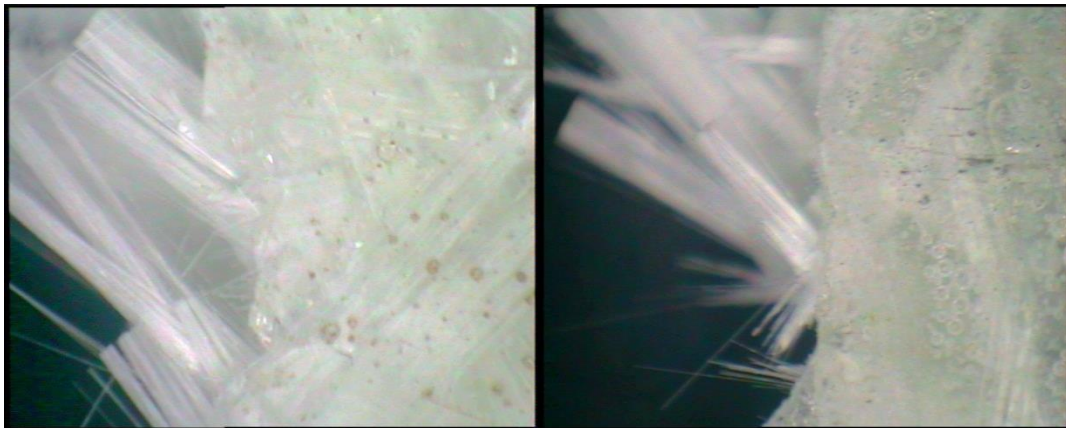


Figure 4.6 (b) Optical microscope images of glass fibre epoxy composite after tensile test

CHAPTER 5

SLIDING WEAR BEHAVIOUR OF E-GLASS FIBRE REINFORCED EPOXY COMPOSITES

The sliding behaviour of uncoated fibre reinforced, fibre and filler reinforced, and aluminium coated fibre reinforced has been studied. The chapter deals with parametric analysis of sliding wear process using Taguchi experimental design. Results of ANOVA study is also reported to understand the effect of various parameters.

5.1 Sliding wear behaviour of E-glass-epoxy composites

5.1.1 Effect of fibre loading on sliding wear behaviour of uncoated and unfilled composites

The variation of wear rate with respect to fibre loading at different testing conditions is shown in Figure 5.1. Specific wear rate of the composites decreases with increase in fibre loading, at C1 testing condition. The hardness plays an important role in the wear resistance of the material. As fibres are harder phase in the composite more energy is required for the failure of the fibres. Thus, the wear failure is less in case of composites with higher fibre loading. At C2 testing condition (sliding velocity 250 rpm, sliding distance 471.23 m and normal load 10 N) minimum specific wear rate is observed in case of composite with 20 wt% fibre loading. Among all the testing conditions (i.e. C1, C2 and C3) composites with 15 wt% fibre loading exhibit minimum specific wear rate [32].

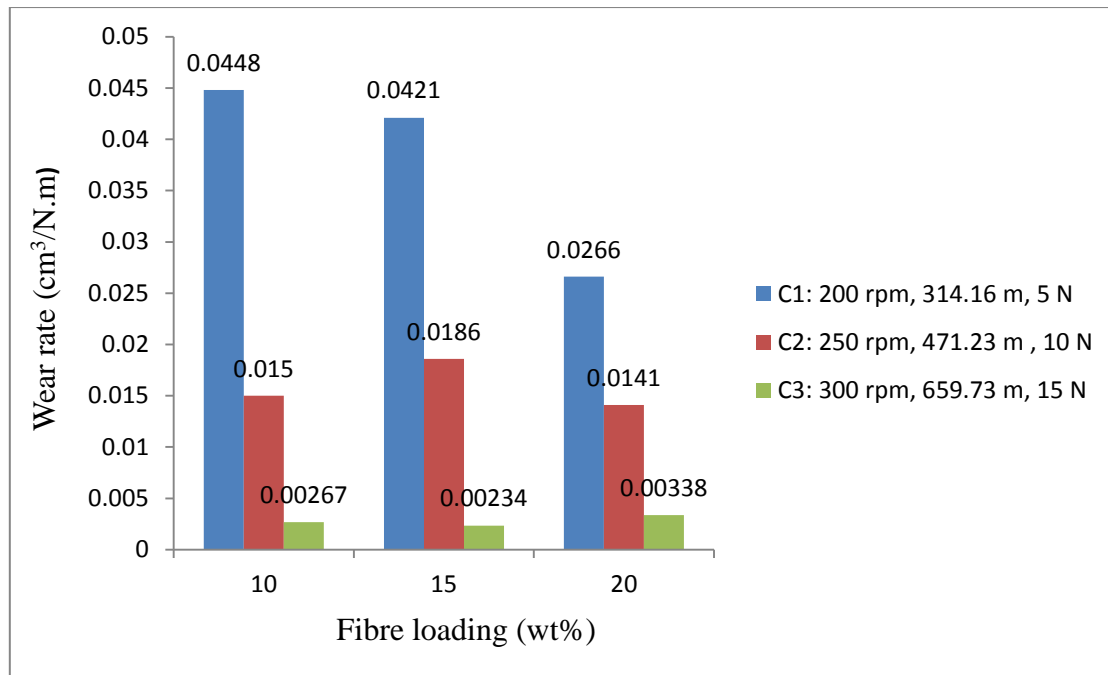


Figure 5.1 Wear rate of uncoated and unfilled composite at different fibre loading and test conditions

5.1.2 Effect of fibre loading on sliding wear behaviour of uncoated and filled composites

The specific wear rate of Al_2O_3 filled composites are shown in Figure 5.2. The filler content is same for all samples. Wear resistance of polymer composites depends on the bonding between filler and matrix, distribution of filler material, fibre loading and also the presence of voids in composite samples. At sliding velocity 200 rpm, sliding distance 314.16 m and normal load 5 N, wear rate increases from 0.0263 to 0.0321 cm^3/Nm with the increase in fibre loading up to 15 wt% beyond which specific wear rate decrease. However, at sliding velocity 250 rpm, sliding distance 471.23 m and normal load 10 N, wear rate gradually decreases with increase in fibre loading [33]. This may due to less voids and uniform distribution of filler and fibre throughout the matrix. But at sliding velocity 300 rpm, sliding distance 659.73 m and normal load 15 N, specific wear rate of specimens is lesser than the those specimens subjected to C2 and C3 test conditions, as observed from Figure 5.2. This may be due to the less contact time during the wear test.

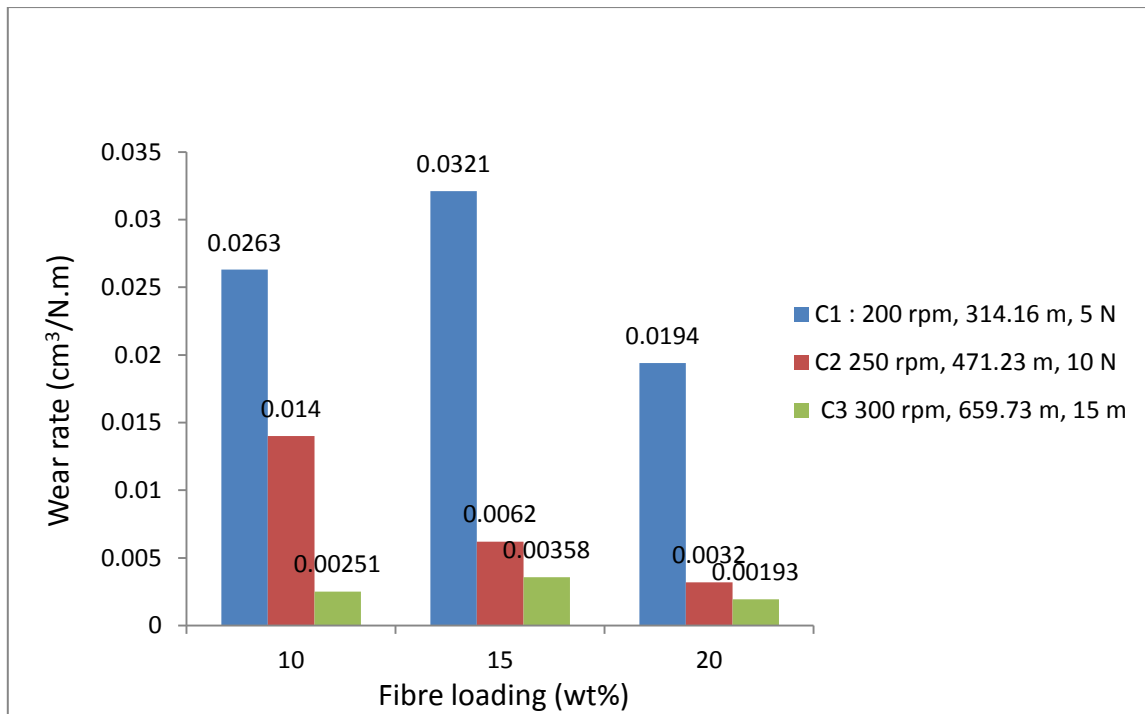


Figure 5.2 Wear rate of uncoated and filled composite at different fibre loading and test conditions

5.1.3 Effect of fibre loading on sliding wear behaviour of coated and unfilled composites

Figure 5.3 shows the specific wear rate of the coated samples at different testing conditions. The maximum wear is observed in case of coated sample with 15 wt% fibre loading which was subjected to test condition of 200 rpm, 314.16 m and 5 N. Minimum specific wear rate of 0.0155 cm³/Nm is observed in case of composite have 20 wt% fibre loading. The samples at C3 testing condition depict the minimum specific wear rate.

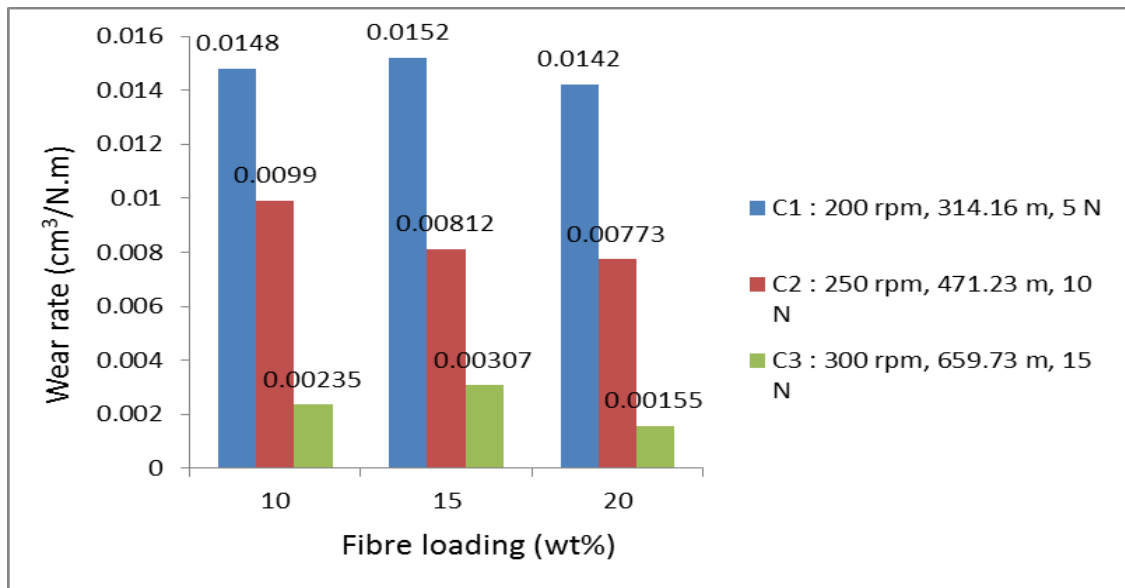


Figure 5.3 Wear rate of coated and unfilled composite at different fibre loading and test conditions

On comparing Figure 5.1, 5.2 and 5.3 it has been found that maximum wear occurs in case of uncoated and unfilled composites. The addition of Al_2O_3 filler in the uncoated composites results in improved wear resistance. The hard Al_2O_3 particles fill the space between the matrix and fibre thus making the composite more brittle and results in low wear. The aluminium coating on the surface of unfilled composites further enhanced the wear resistance of the composites. When the aluminium coated samples comes in contact with the environment formation of oxides layer takes place and during the sliding wear this oxide film breaks and provide the lubricating effect which in turn reduces the wear of the composites.

5.2 Taguchi experimental result

Table shows the Taguchi orthogonal array used for the present study. Column 2, 3 4, 5, 6 and 7 shows various factors (i.e. filler content, coating thickness, sliding velocity, sliding distance, normal load and fibre loading) and there levels. Each row shows the experimental condition i.e. combination of various parameters and levels under which the composites were subjected to sliding wear test. Column 8 depicts the value of specific wear rate of each

testing condition. The overall mean value for the S/N ratio of specific wear rate for 36 different iterations is found to be 41.23 db. From the Figure 5.4 it is observed that factor combination of filler content of 5 %, coating thickness of 0.25 %, sliding speed of 0.6280 m/s, sliding distance of 659.73 m, normal load of 10 N and fibre loading of 20 wt% gives minimum specific wear rate.

Table 5.1 Test conditions with output results using mixed type L_{36} orthogonal array

S. No.	Filler content A (%)	Coating thickness B (μm)	Sliding velocity C (rpm)	Sliding distance D (m)	Normal load (N) E (N)	Fibre loading F (%)	Sp. Wear rate ($\text{cm}^3/\text{N-m}$)	S/N ratio (db)
1	0	0	0.5230	314.16	5	10	0.0420	27.457
2	0	0	0.7854	471.23	10	15	0.0186	34.6097
3	0	0	1.1000	659.73	15	20	0.0267	33.3302
4	0	0	0.5230	314.16	5	10	0.0448	26.9744
5	0	0	0.7854	471.23	10	15	0.0186	34.6097
6	0	0	1.1000	659.73	15	20	0.0147	36.6536
7	0	0	0.5230	314.16	10	20	0.0246	32.1813
8	0	0	0.7854	471.23	15	10	0.0235	32.5786
9	0	0	1.1000	659.73	5	15	0.0228	32.8413
10	0	0.25	0.5230	314.16	15	15	0.0147	36.6537
11	0	0.25	0.7854	471.23	5	20	0.0124	38.1316
12	0	0.25	1.1000	659.73	10	10	0.00234	52.6157
13	0	0.25	0.5230	471.23	15	10	0.0116	38.7108
14	0	0.25	0.7854	659.73	5	15	0.00531	45.4981
15	0	0.25	1.1000	314.16	10	20	0.0102	39.8280
16	0	0.25	0.5230	471.23	15	15	0.0153	36.3062
17	0	0.25	0.7854	659.73	5	20	0.00312	50.1169
18	0	0.25	1.1000	314.16	10	10	0.0125	38.0618
19	5	0	0.5230	471.23	5	20	0.00631	43.9994
20	5	0	0.7854	659.73	10	10	0.00257	51.8013
21	5	0	1.1000	314.16	15	15	0.0273	31.2767
22	5	0	0.5230	471.23	15	20	0.00464	46.6696
23	5	0	0.7854	659.73	10	10	0.00473	46.5028
24	5	0	1.1000	314.16	5	15	0.0334	29.5251
25	5	0	0.5230	659.73	10	10	0.00778	42.1804
26	5	0	0.7854	314.16	15	15	0.0314	30.0614
27	5	0	1.1000	471.23	5	20	0.00346	49.2185
28	5	0.25	0.5230	659.73	10	20	0.00142	56.9542
29	5	0.25	0.7854	314.16	15	15	0.0136	37.3292
30	5	0.25	1.1000	471.23	5	10	0.00423	47.4732
31	5	0.25	0.5230	659.73	15	20	0.00104	59.6593
32	5	0.25	0.7854	314.16	5	10	0.0144	36.8328

33	5	0.25	1.1000	471.23	10	15	0.00582	44.7015
34	5	0.25	0.5230	659.73	5	15	0.01761	35.0848
35	5	0.25	0.7854	314.16	10	20	0.00315	50.0338
36	5	0.25	1.1000	471.23	5	10	0.00232	52.6902

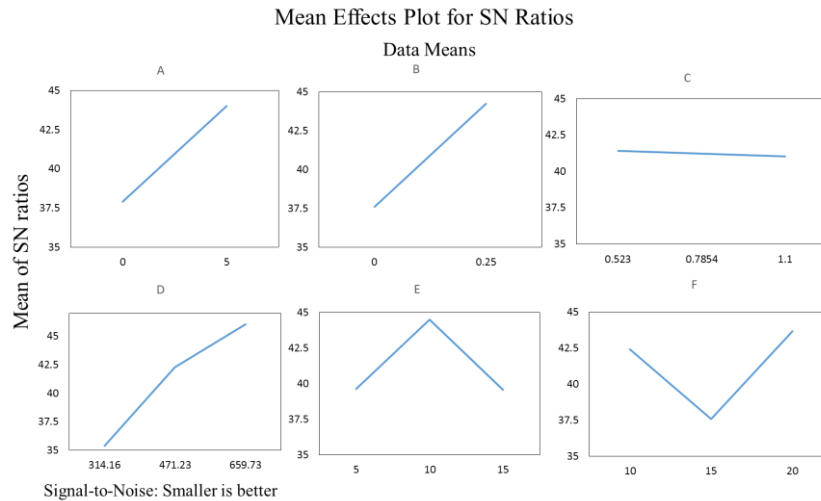


Figure 5.4 Effect of control factors on specific wear rate for glass-epoxy composites

Table 5.2 ANOVA table for wear rate

Source	DOF	Seq SS	Adj SS	Adj MS	F	P
A	1	303.02	376.725	376.725	14.74	0.001
B	1	436.46	436.464	436.464	17.07	0.0001
C	2	0.76	5.168	2.2584	0.10	0.904
D	2	647.62	675.903	337.952	13.22	0.0001
E	2	197.43	160.390	80.195	3.14	0.063
F	2	202.52	202.524	101.262	3.96	0.034
Residual Error	22	562.45	562.453	25.566		
Total	32	2350.28				

To determine the statistical significance of various factor like filler content (A), coating thickness (B), sliding velocity (C), sliding distance (D), normal load (E), fibre percentage (F) on wear rate, analysis of variance ANOVA is done on wear rate. A significance level of significance 5% is considered for this study. The p-value shown in last column of ANOVA Table shows the significance of individual factors and their interactions. Lower the p-value higher the significance level of factors.

From Table it is observed that filler content ($p=0.001$), coating thickness ($p<0.001$), sliding distance ($p < 0.001$) and fibre loading ($p = 0.034$) has significant effect on specific wear rate of composites. Whereas sliding velocity ($p=.904$) and normal load ($p=0.063$) has less effect on specific wear rate.

5.3 Surface Morphology of Composite before and after wear test

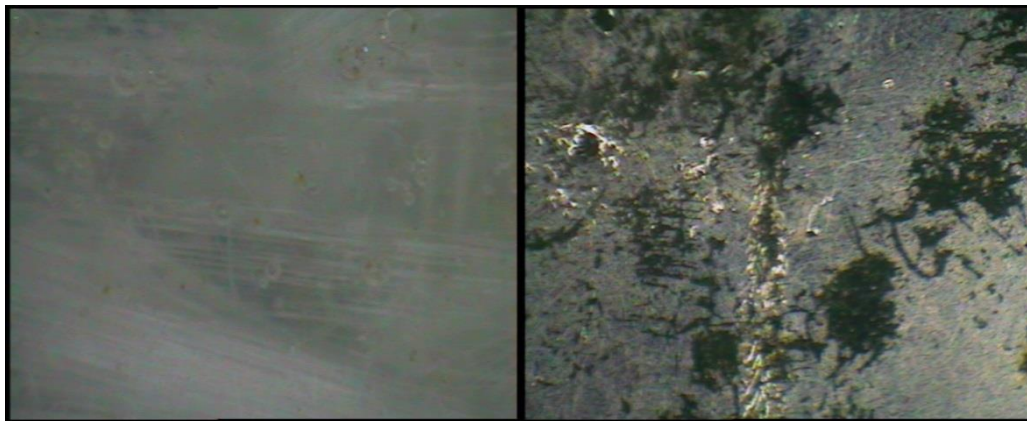
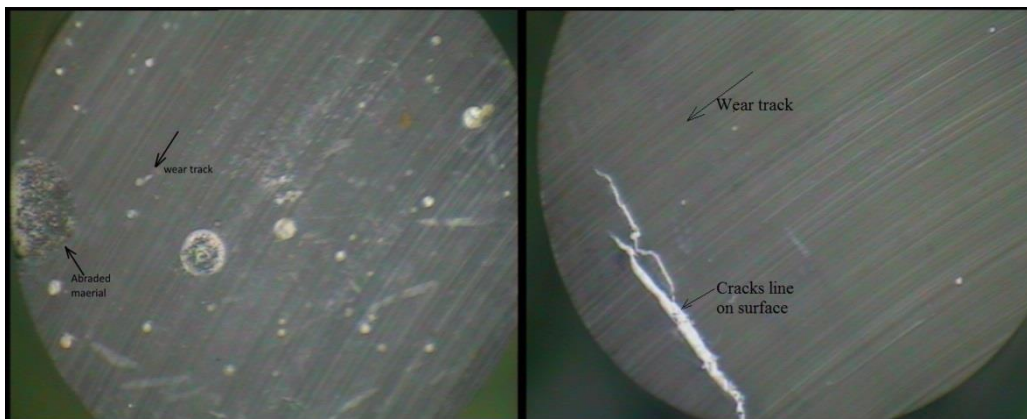


Figure 5.5 (a) Optical microscope images of glass-epoxy composite before wear test



5.5 (b) Optical microscope images of glass-epoxy composite after wear test

CHAPTER 6

CONCLUSIONS

The experimental work done on the effect of fibre loading, filler content on mechanical and also the effect of coating on sliding wear behaviour of E-glass reinforced epoxy composite leads to obtained the following conclusions from the present study as follows:

1. Fabrication of E- glass fibre reinforced epoxy composites with and without filler composites is done using simple hand lay-up technique.
2. Thin film coating of aluminium on glass-fibre reinforced epoxy composites is done by using thermal evaporation technique. The coating thickness of 0.25 μm is achieved over the surface of fabricated composites.
3. The addition of glass fibre in the composites improves the mechanical property of polymer resin. The hardness and tensile strength of the composite increases with the increase in fibre loading. Flexural strength and impact strength of the fibre reinforced composites increased up to an optimum level of fibre loading.
4. Hardness, flexural and tensile properties of the glass epoxy composites are enhanced with addition of Al_2O_3 filler in the glass-epoxy composites.
5. The addition of filler in to the glass-epoxy composites results in improved sliding wear resistance of the glass-epoxy composites. However, the aluminium coated glass-epoxy composites shows minimum specific wear rate on comparing with glass-epoxy composites and Al_2O_3 filled glass-epoxy composites.

6. The factor combination of filler content of 5 %, coating thickness of 0.25 %, sliding speed of 0.6280 m/s, sliding distance of 659.73 m, normal load of 10 N and fibre loading of 20 wt% gives minimum specific wear rate.
7. ANOVA study reveals that filler content, coating thickness, sliding distance and fibre loading has significant effect on specific wear rate of glass-epoxy composites.

Scope for future work

There is wide scope for the future researchers to explore this field of research. This work can be further extended to investigate the other aspects of coated composites like use of other potential coating materials for the development of hybrid composites and evaluation of their wear and mechanical properties.

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